# MATH2111 Higher Several Variable Calculus Curves and Surfaces 

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Semester 1, 2014


UNSW

## Welcome to MATH2111

- Lecturer weeks 1 to 5 and 12: Dr Jonathan Kress
- Lecturer weeks 6 to 11: A/Prof Josef Dick
- Tutorials start in week 2.
- Moodle http://moodle.telt.unsw.edu.au will have lecture notes, videos of the week 1 to 6 lectures from 2011 lectures, tutorial problems etc.
- MATH2111 is a significantly more difficult than MATH2011. If you have any concerns about whether you should take MATH2011 or MATH2111, please discuss this with the lecturer as soon as possible.
- Read the course outline - a link is on the Moodle course page.
- Information on the writing assignment will be available in week 3.


## Curves

## Definition

A curve in $\mathbb{R}^{n}$ is a vector valued function

$$
\mathbf{c}: I \rightarrow \mathbb{R}^{n}
$$

where $/$ is an interval on $\mathbb{R}$.


Often we think of the image of $I$ under $\mathbf{c}$ as the curve, but this is not the definition.

The function $\mathbf{c}$ is also called a parameterisation.

## Curves

Example: A curve (or parameterisation) $\mathbf{r}:[-1,3] \rightarrow \mathbb{R}^{2}$ is given by

$$
\mathbf{r}(t)=\left(1+t, \frac{4}{3} t^{2}\right) .
$$

The image of $[-1,3]$ is

$$
\left\{(x, y): x=1+t, y=\frac{4}{3} t^{2},-1 \leq t \leq 3\right\} .
$$

Plot and label the points $\mathbf{r}(-1), \mathbf{r}(0), \mathbf{r}(1), \mathbf{r}(2)$ and $\mathbf{r}(3)$. Find a Cartesian equation for the image of $[-1,3]$ and sketch the curve. Indicate the direction of increasing parameter.

A Cartesian equation can be obtained by eliminating the parameter.
$x=1+t, y=\frac{4}{3} t^{2} \quad \Rightarrow \quad y=\frac{4}{3}(x-1)^{2}$.


## Curves

Examples: Sketch the following curves.
$\mathbf{r}:[0, \pi] \rightarrow \mathbb{R}^{2}$ given by

$$
\mathbf{r}(t)=\cos t \mathbf{i}+\sin t \mathbf{j}
$$

$$
\begin{aligned}
& r:[0, \pi) \rightarrow \mathbb{R}^{2} \\
& r(t)=\cos k i+\sin k j
\end{aligned}
$$


$\mathbf{r}:[0,6 \pi] \rightarrow \mathbb{R}^{3}$ given by

$$
\mathbf{r}(t)=\cos t \mathbf{i}+\sin t \mathbf{j}+t \mathbf{k}
$$

$$
\begin{aligned}
& \underline{r}:[0,6 \pi] \rightarrow \mathbb{R}^{3} \\
& \underline{r}(t)=\cos t \underline{i}+\sin t \underline{j}+t \underline{k}
\end{aligned}
$$



## Curves

## Example

Find two different curves with the image drawn below. For each curve, describe the direction of increasing parameter.


Give a parameterisation that traverses from $B$ to $A$ and another that traverses from $A$ to $B$ and then back to $A$ again.

## Curves

Example: Sketch $\mathbf{r}:[0,20] \rightarrow \mathbb{R}^{2}$ given by $\mathbf{r}(t)=\left(\cos t+\frac{1}{3} t\right) \mathbf{i}+\sin t \mathbf{j}$.


## Curves

## Definition

- A multiple point is a point through which the curve passes more than once.
- For a curve $\mathbf{c}:[a, b] \rightarrow \mathbb{R}^{n}, \mathbf{c}(a)$ and $\mathbf{c}(b)$ are called end points.
- A curve is closed if its end points are the same point.

Which of the following are the image of a closed curve? How many multiple points (other than end points) does each curve have?

$\mathbf{A}$ and $\mathbf{B}$ are closed. $\mathbf{B}$ and $\mathbf{D}$ have one multiple point each.
What assumption has been made in the above answers?

## Limits and Calculus for Curves

## Definition

For an interval $I \subset \mathbb{R}$ and curve $\mathbf{c}: I \rightarrow \mathbb{R}^{n}$ with

$$
\mathbf{c}(t)=\left(c_{1}(t), c_{2}(t), \ldots, c_{n}(t)\right)
$$

the functions $c_{i}: I \rightarrow \mathbb{R}, i=1,2, \ldots, n$ are called the components of $\mathbf{c}$.

Define limits, derivatives and integrals component by component.

## Definition

- $\lim _{t \rightarrow a} \mathbf{c}(t)=\left(\lim _{t \rightarrow a} c_{1}(t), \lim _{t \rightarrow a} c_{2}(t), \ldots, \lim _{t \rightarrow a} c_{n}(t)\right)$
- $\frac{d \mathbf{c}(t)}{d t}=\dot{\mathbf{c}}(t)=\mathbf{c}^{\prime}(t)=\left(c_{1}^{\prime}(t), c_{2}^{\prime}(t), \ldots, c_{n}^{\prime}(t)\right)$
- $\int_{a}^{b} \mathbf{c}(t) d t=\left(\int_{a}^{b} c_{1}(t) d t, \int_{a}^{b} c_{2}(t) d t, \ldots, \int_{a}^{b} c_{n}(t) d t\right)$


## Limits and Calculus for Curves

## Definition

A curve $\mathbf{c}: I \rightarrow R^{n}$ is

- continuous if its component functions are continuous.
- simple if it is continuous and has no multiple points (other than the end points if it is closed).
- smooth if its components are differentiable and their derivatives do not simultaneouly vanish.
- piecewise smooth if it is made up of a finite number of smooth curves.

A curve has an orientation - the direction of increasing $t$.
We will revisit continuity in the analysis section and give a different definition which we will show is equivalent.

## Limits and Calculus for Curves

Example: $\mathbf{r}:[-2,2] \rightarrow \mathbb{R}^{2}$ with $\mathbf{r}(t)=\left(t^{2}+1, t^{3}+1\right)$ is not smooth.


## Differentiation Rules for Curves

Working component by component we can prove the following rules from their one variable counterparts.

$$
\begin{aligned}
\frac{d}{d t}\left(\mathbf{c}_{\mathbf{1}}(t)+\mathbf{c}_{\mathbf{2}}(t)\right) & =\frac{d \mathbf{c}_{\mathbf{1}}(t)}{d t}+\frac{d \mathbf{c}_{\mathbf{2}}(t)}{d t} \\
\frac{d}{d t}(\lambda \mathbf{c}(t)) & =\lambda \frac{d \mathbf{c}(t)}{d t} \\
\frac{d}{d t}(f(t) \mathbf{c}(t)) & =\frac{d f(t)}{d t} \mathbf{c}(t)+f(t) \frac{d \mathbf{c}(t)}{d t} \\
\frac{d}{d t}\left(\mathbf{c}_{\mathbf{1}}(t) \cdot \mathbf{c}_{\mathbf{2}}(t)\right) & =\frac{d \mathbf{c}_{\mathbf{1}}(t)}{d t} \cdot \mathbf{c}_{\mathbf{2}}(t)+\mathbf{c}_{\mathbf{1}}(t) \cdot \frac{d \mathbf{c}_{\mathbf{2}}(t)}{d t} \\
\frac{d}{d t}\left(\mathbf{c}_{\mathbf{1}}(t) \times \mathbf{c}_{\mathbf{2}}(t)\right) & =\frac{d \mathbf{c}_{\mathbf{1}}(t)}{d t} \times \mathbf{c}_{\mathbf{2}}(t)+\mathbf{c}_{\mathbf{1}}(t) \times \frac{d \mathbf{c}_{\mathbf{2}}(t)}{d t} \\
\frac{d}{d t}(\mathbf{c}(f(t))) & =\mathbf{c}^{\prime}(f(t)) f^{\prime}(t)
\end{aligned}
$$

$$
\begin{aligned}
\frac{d \mathbf{c}(t)}{d t} & =\left(c_{1}^{\prime}(t), \ldots, c_{n}^{\prime}(t)\right) \\
& =\left(\lim _{h \rightarrow 0} \frac{c_{1}(t+h)-c_{1}(t)}{h}, \ldots, \lim _{h \rightarrow 0} \frac{c_{n}(t+h)-c_{n}(t)}{h}\right) \\
& =\lim _{h \rightarrow 0}\left(\frac{c_{1}(t+h)-c_{1}(t)}{h}, \ldots, \frac{c_{n}(t+h)-c_{n}(t)}{h}\right) \\
& =\lim _{h \rightarrow 0} \frac{\mathbf{c}(t+h)-\mathbf{c}(t)}{h}
\end{aligned}
$$



As $h$ gets smaller, the direction of $\mathbf{c}(t+h)-\mathbf{c}(t)$ approaches the direction of the tangent to the curve's image. If $\mathbf{c}^{\prime}(t)$ exists and is non-zero, it is called the tangent vector to $\mathbf{c}$ at $t$, or the velocity of $\mathbf{c}$ at $t$. le, $\mathbf{v}(t)=\mathbf{c}^{\prime}(t)$. The speed of $\mathbf{c}$ at $t$ is $|\mathbf{v}(t)|=\sqrt{\mathbf{v}(t) \cdot \mathbf{v}(t)}$.
The second derivative $\mathbf{a}(t)=\mathbf{v}^{\prime}(t)=\mathbf{c}^{\prime \prime}(t)$ is called the acceleration.

## Tangent Vector Example

Consider the curve $\mathbf{r}: I \rightarrow \mathbb{R}^{3}$ for an interval $I \subset \mathbb{R}$ given by

$$
\mathbf{r}(t)=2 \cos t \mathbf{i}+3 \sin t \mathbf{j}+\frac{\sqrt{5}}{2} \cos 2 t \mathbf{k} .
$$

a) Find the velocity and acceleration vectors.
b) Show that the velocity and acceleration vectors are perpendicular at $t=\frac{n \pi}{2}$, $n \in \mathbb{Z}$.
c) Find the length of the curve between $\mathbf{r}(0)$ and $\mathbf{r}(2 \pi)$.
[Recall: length $=\int_{a}^{b}\left\|\mathbf{r}^{\prime}(t)\right\| d t$.]
d) Find the unit tangent vector at $t=\frac{\pi}{6}$.
e) Sketch the curve and indicate the unit tangent vector found in (d).

## Surfaces

You have seen surfaces in $\mathbb{R}^{3}$ described in 3 ways.

Graph of a function


Eg, $z=f(x, y)$

Implicitly


Eg , a sphere given by $x^{2}+y^{2}+z^{2}=1$.

## Parametrically



Eg , a plane given by $\mathbf{x}=\mathbf{x}_{\mathbf{0}}+\lambda_{1} \mathbf{v}_{1}+\lambda_{\mathbf{2}} \mathbf{v}_{2}$.

## Parameterisation defined surface

For $D \subset \mathbb{R}^{2}$, the image of $D$ under $\mathbf{r}: D \rightarrow \mathbb{R}^{3}$ is a surface in $\mathbb{R}^{3}$. Note that unlike for curves, a surface is the image of the parameterisation.


Eg, $\mathbf{r}: D \rightarrow \mathbb{R}^{3}$ where $D=\left\{(x, y): x^{2}+y^{2} \leq 1\right\}$ and

$$
\mathbf{r}(s, t)=\left(s, t, \sqrt{1-s^{2}-t^{2}}\right)
$$

is a parameterisation of the upper unit hemisphere.

## Implicitly defined surface

We can define a surface in $\mathbb{R}^{3}$ as the set of points satisfying an equation. Eg , a sphere given by $x^{2}+y^{2}+z^{2}=1$.


Later in the course we will study a theorem that tells you when parts of this surface are the graph of a function of some of the variables - the Implicit Function Theorem.

Some other implicitly defined surfaces will be discussed in tutorial 1 .

## Graphs of functions of one variable

The graph of

$$
f: \mathbb{R} \rightarrow \mathbb{R}
$$

is the set of points

$$
\left\{(x, y) \in \mathbb{R}^{2}: y=f(x)\right\} .
$$



On the graph of $f$, input values are represented by distance across the page and output values by distance up the page.

## Graphs of functions of two variables

The graph of

$$
f: D \rightarrow \mathbb{R}
$$

is the set of points

$$
\begin{gathered}
\{(x, y, z): z=f(x, y) \\
\quad \text { for all }(x, y) \in D\}
\end{gathered}
$$

In this example the domain is the subset of $\mathbb{R}^{2}$ shaded pink in the diagram.

In other examples, it could be all of $\mathbb{R}^{2}$ or any other subset of $\mathbb{R}^{2}$.


Note the orientation of the axes. If you sat on top of $z$-axis and looked down, you would see the usual orientation for the $x$ and $y$ axes.

## Graphs of functions of two variables

Given a function of two variables, how can we visualise it?
For example, what does the graph of

$$
f: \mathbb{R}^{2} \rightarrow \mathbb{R}, \quad f(x, y)=x^{2}+y^{2}
$$

look like. That is, we want to sketch the set of points in $\mathbb{R}^{3}$ satisfying $z=f(x, y)$.
Let's start by looking at some vertical slices with constant $x$.


Next put these together.

## Graphs of functions of two variables




We could also take slices of constant $y$. Try plotting these yourself.

## Horizontal slices

We could also take horizontal slices, that is, slices of constant $z$.

$$
\begin{array}{lllll}
z & =-1 & : & \text { no solution } & \\
z & =0 & : & (x, y)=(0,0) & \text { a single point } \\
z & =1 & : & x^{2}+y^{2}=1 & \text { a circle of radius } 1 \\
z & =2 & : & x^{2}+y^{2}=2 & \text { a circle of radius } \sqrt{2} \\
& \text { etc } & & &
\end{array}
$$



Horizontal slices

If we plot the horizontal slices in the $x y$-plane, we have a contour map.


We have plotted some level curves or contours of $f$.
Contours or other slices are a good way of visualising a surface.

Level curves - examples

Contours on topographical maps are used to describe a surface. Maps Downunder have some sample maps on their website.
http://www.mapsdownunder.com.au/cgi-bin/mapshop/ABC-MTPKT.html


## Level curves - examples

```
> f1 := 1-sin((x^2+y^2)/40)^2:
> with(plots):
    plot3d(f1,x=-10..10,y=-10..10,
    axes=normal,transparency=0.5,
```

    labels=[x,y,z],grid=[30,30]);
    

Level curves - examples





## Level curves - example



Let $f$ be a function of two variables. The $f(x, y)=0.5,1.0,1.5,2.0,2.5,3.0,3.5,4.0$ level curves are draw on the left.

Which of the surfaces below could be the graph $z=f(x, y)$ ? Give reasons for your choice



## Surfaces - an example

Sketch the level curves of

$$
f(x, y)=4-\sqrt{x^{2}+y^{2}}
$$

and describe the surface $z=f(x, y)$.



$$
\begin{aligned}
& z=f(x, y)=4-\sqrt{x^{2}+y^{2}} \\
& \text { level under) are } c=4-\sqrt{x^{2}+y^{2}} \\
& \begin{aligned}
\Rightarrow c-4=-\sqrt{x^{2}+y^{2}} & (\text { Note } c-4 \leqslant 0 \\
& \Rightarrow c \leqslant 4)
\end{aligned} \\
& c=4: \quad(x, y)=(0,0) \\
& c=3: x^{2}+y^{2}=1 \\
& c=1: x^{2}+y^{2}=9
\end{aligned}
$$

## Surfaces - an example

Sketch the level curves of

$$
f(x, y)=\sqrt{1-x^{2}-3 y^{2}}
$$

and describe the surface $z=f(x, y)$.

$$
\left.\begin{array}{l}
z=f(x, y)=\sqrt{1-x^{2}-3 y^{2}} \\
\text { level curves ar } \quad c=\sqrt{1-x^{2}-3 y^{2}} \\
\Rightarrow x^{2}+3 y^{2}=1-c^{2} \quad(c \geqslant 0) \\
c=1:(x, y)=(q, 0) \\
c=\frac{3}{4}: x^{2}+3 y^{2}=\frac{3}{4} \frac{7}{16} \\
c=\frac{1}{2}: x^{2}+3 y^{2}=\frac{3}{4} \\
c=\frac{1}{4}: x^{2}+3 y^{2}=\frac{15}{16} \\
c=0: x^{2}+3 y^{2}=1
\end{array}\right\} \text { ellipses }
$$




